Eunok Bae



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02

Review: VQAs QAOA



MAX-CUT problem



Implementing QAOA



## **Variational Quantum Algorithms**

✓ What is VQAs?

✓ VQE and QAOA

#### **Variational Quantum Algorithms**

What is VQAs?

Variational Quantum-Classical Simulations



[W.W. Ho and T.H. Hsieh, Efficient variational simulation of non-trivial quantum states, SciPost Phys. 6, 029 (2019)]



#### Variational Quantum Eigensolver (VQE)

What is VQE?



[J. Tilly et al., The Variational Quantum Eigensolver: A review of methods and best practices, Physics Reports 986 1–128 (2022)]



#### **Variational Quantum Algorithms**

What is VQAs?



[M. Cerezo et al., Variational quantum algorithms,, Nature Reviews Physics 3, pages 625-644 (2021)]



## **Variational Quantum Algorithms**

 $\oslash$  What is VQAs?

⊘ VQE and **QAOA** 



What is QAOA?



- ✓ QAOA was introduced by Farhi *et al.* (2014)
- Apply VQE framework to solve classical optimization problem by setting

 $H = \sum_{x \in \{0,1\}^n} C(x) |x\rangle \langle x|$ 

where C(x) is a cost function.

 $|0\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, |1\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ 

$$|0\rangle\langle 0| = \begin{pmatrix} 1\\0 \end{pmatrix}(1 \ 0) = \begin{pmatrix} 1\\0 \ 0 \end{pmatrix}$$
$$|1\rangle\langle 1| = \begin{pmatrix} 0\\1 \end{pmatrix}(0 \ 1) = \begin{pmatrix} 0\\0 \ 1 \end{pmatrix}$$

$$C(0)|0\rangle\langle 0| + C(1)|1\rangle\langle 1| = \begin{pmatrix} C(0) & 0\\ 0 & C(1) \end{pmatrix}$$

[E. Farhi et al., A Quantum Approximate Optimization Algorithm, arXiv:1411.4028 (2014)]



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✓ The ground state of H = the lowest-cost x

 $H = C(0)|0\rangle\langle 0| + C(1)|1\rangle\langle 1| = \begin{pmatrix} C(0) & 0\\ 0 & C(1) \end{pmatrix}$ 

$$\langle 0|H|0\rangle = (1 \ 0) \begin{pmatrix} C(0) & 0 \\ 0 & C(1) \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = C(0) \langle 1|H|1\rangle = (0 \ 1) \begin{pmatrix} C(0) & 0 \\ 0 & C(1) \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = C(1)$$

Generally,  $\min_{x \in \{0,1\}^n} \langle x | H | x \rangle = \min_{x \in \{0,1\}^n} C(x)$ 

[E. Farhi et al., A Quantum Approximate Optimization Algorithm, arXiv:1411.4028 (2014)]



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Cut = 4

[E. Farhi et al., A Quantum Approximate Optimization Algorithm, arXiv:1411.4028 (2014)]

# **MAX-CUT** problem



#### **MAX-CUT** problem

What is MAX-CUT problem?

MAX-CUT Problem

 ✓ Goal: Split the set of vertices V of a graph G into two disjoint parts such that the number of edges spanning two parts is maximized





#### **MAX-CUT** problem

What is MAX-CUT problem?

MAX-CUT Problem

✓ Formulated as an optimization problem : for  $z = (z_1, \dots, z_N)$ ,  $z_i \in \{-1, 1\} \forall i$ 



# Weighted MAX-CUT problem

#### Weighted MAX-CUT problem

What is the weighted MAX-CUT problem?

Weighted MAX-CUT Problem

✓ Weighted undirected graph: G = (V, E) with edge weight  $w_{ij} > 0$ ,  $w_{ij} = w_{ji}$  for  $(i, j) \in E$ 





#### Weighted MAX-CUT problem

What is the weighted MAX-CUT problem?

Weighted MAX-CUT Problem

✓ Formulated as an optimization problem : for  $\mathbf{z} = (z_1, \dots, z_N)$ ,  $z_i \in \{-1, 1\} \forall i$ 

$$\max_{\mathbf{z}} C(\mathbf{z}) = \max_{2} \frac{1}{2} \sum_{\{i,j\} \in E} \mathbf{w}_{ij} (1 - z_i z_j)$$

or, equivalently, for  $\mathbf{x} = (x_1, \dots, x_N)$ ,  $x_i \in \{0, 1\} \forall i$ 

$$\max_{\mathbf{x}} C(\mathbf{x}) = \max \frac{1}{2} \sum_{\{i,j\} \in E} \mathbf{w}_{ij} (1 - (-1)^{x_i} (-1)^{x_j})$$
$$= \max \sum_{\{i,j\} \in E} \mathbf{w}_{ij} (1 - x_i) x_j$$



#### Weighted MAX-CUT problem

Applications of the weighted MAX-CUT problem

✓ Marketing model :

 $w_{ij}$  = probability that the person j will buy a product after i gets a free one







QAOA for MAX-CUT Problem

QAOA for MAX-CUT Problem

✓ MAX-CUT Hamiltonian:

Pauli matrices  $H_C = \frac{1}{2} \sum_{\{i,j\} \in E} (1 - Z_i Z_j) \qquad \qquad X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, Y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, Z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ 

 $\checkmark \text{ Note that } Z_i \equiv I \otimes \cdots \otimes Z \otimes \cdots \otimes I \text{ and } Z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \qquad Z|0\rangle = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = |0\rangle, \qquad Z|1\rangle = -|1\rangle$   $\uparrow \text{ i-th}$ 

 $\begin{aligned} Z_i Z_j &= I \otimes \cdots \otimes Z \otimes \cdots \otimes Z \otimes \cdots \otimes I \\ \uparrow \quad \text{i-th} \quad \uparrow \quad \text{j-th} \end{aligned}$ 

 $\checkmark \quad H_C|x\rangle = C(x)|x\rangle \quad \forall x \in \{0,1\}^N$ 

 $Z_0 Z_2 |1000\rangle = Z |1\rangle \otimes |0\rangle \otimes Z |0\rangle \otimes |0\rangle$ 

$$\checkmark \ \max_{x} C(x) = \max_{x} \frac{1}{2} \sum_{\{i,j\} \in E} (1 - (-1)^{x_i} (-1)^{x_j}) = \max_{z} C(z)$$

 $= -|1000\rangle$  $= (-1)^{x_0} (-1)^{x_2} |1000\rangle$ 

#### Variational Quantum Eigensolver (VQE)

Some variational ansatze - targeted at quantum simulation

- ✓ Hamiltonian Variational ansatz:
- Assume that: we want to find the ground state of  $H = \sum_i H_i$

we can write  $H = H_B + H_C$ 

1 easy to prepare the ground state of  $H_B$ 

• Then: prepare the ground state of  $H_A$ 

For each of *L* layers *l*, implement  $\prod_k e^{it_{lk}H_k}$  for some times  $t_{lk} \in \mathbb{R}$ 

• Intuition comes from the **quantum adiabatic theorem**:

As  $L \rightarrow \infty$ , this ansatz provably can represent the ground state of *H*.



What is QAOA?

- 1. Initialize the quantum processor in  $|+\rangle^{\otimes N}$
- 2. Generate a variational wavefunction  $|\psi_p(\vec{\gamma}, \vec{\beta})\rangle = \frac{e^{-i\beta_p H_B}e^{-i\gamma_p H_C} \cdots e^{-i\beta_1 H_B}e^{-i\gamma_1 H_C}}{|+\rangle^{\otimes N}}$ by applying the problem Hamiltonian  $H_C$  and a mixing Hamiltonian  $H_B = \sum_{j=1}^N X_j$
- 3. Determine the expectation value

 $F_p(ec{m{\gamma}},ec{m{eta}}) = \langle \psi_p(ec{m{\gamma}},ec{m{eta}}) | H_C | \psi_p(ec{m{\gamma}},ec{m{eta}}) 
angle_{m{eta}}$ 

4. Search for the optimal parameters  $(\vec{\gamma}^*, \vec{\beta}^*) = \arg \max_{\substack{\vec{\gamma}, \vec{\beta}}} F_p(\vec{\gamma}, \vec{\beta})$ by a classical computer



[L. Zhou et al., Quantum Approximate Optimization Algorithm: Performance, Mechanism, and Implementation on Near-Term Devices, Phys. Rev. X 10, 021067, 2020]

**Approximation ratio** 

$$r = rac{F_p(ec{m{\gamma}}^*, ec{m{eta}}^*)}{C_{\max}}$$

## **Limitations of QAOA**



What is QAOA?

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angle_p$ 

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Approximation ratio 
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Limitations of QAOA

#### Bipartite D-regular graph (2019)

For every integer  $D \ge 3$ ,  $\exists$  an infinite family of bipartite D-regular graphs  $\{G_n\}$  such that

$$\frac{1}{|E|} \langle +^n | U^{-1} H_n U | +^n \rangle \le \frac{5}{6} + \frac{\sqrt{D-1}}{3D}$$

for any level-p QAOA circuit  $U \equiv U(\beta, \gamma)$ 

as long as

$$p < (1/3 \log_2 n - 4) D^{-1}$$

where

$$H_n = \frac{1}{2} \sum_{(u,v)\in E} (I - Z_u Z_v)$$



[S. Bravyi et al., Obstacles to State Preparation and Variational Optimization from Symmetry Protection, Phys. Rev. Lett. 125, 260505 (2019)]



Limitations of QAOA

#### Ring of disagrees (2019)

Let  $H_n$  be the ring of disagrees Hamiltonian

$$H_n=rac{1}{2}\sum_{p\in\mathbb{Z}_n}(I-Z_pZ_{p+1}),$$

when n is even.

Let *U* be a  $Z_2$ -symmetric unitary with range R < n/4. Then

$$\frac{1}{n} \langle +^n | U^{\dagger} H_n U | +^n \rangle \leq \frac{2R + 1/2}{2R + 1}.$$



[S. Bravyi et al., Obstacles to State Preparation and Variational Optimization from Symmetry Protection, Phys. Rev. Lett. 125, 260505 (2019)]



# Thank you!

eobae@kias.re.kr